



SDI Review Form 1.6

Journal Name:	Asian Research Journal of Mathematics
Manuscript Number:	Ms_ARJOM_54403
Title of the Manuscript:	STABILITY AND CONTROLLABILITY OF NONLINEAR SYSTEMS
Type of the Article	Original Research Article

General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound. To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<http://www.sciencedomain.org/page.php?id=sdi-general-editorial-policy#Peer-Review-Guideline>)

PART 1: Review Comments

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Compulsory REVISION comments		
Minor REVISION comments		
Optional/General comments	In this paper, the authors obtain new stability and controllability results for nonlinear systems using the Lyapunov indirect method and controllability of the system by the rank criterion for properness. The obtained results are correct. An example is given with a real-life application to illustrate the effectiveness of the theoretical results. This is the most important part of the paper. Real-life applications are very significant for this area. So I recommend the paper for publication.	

PART 2:

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Are there ethical issues in this manuscript?	<i>(If yes, Kindly please write down the ethical issues here in details)</i>	

Reviewer Details:

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